

Design of an Ergonomic Tool for People With Upper Limb Prosthesis



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INTRODUCTION

A hand prosthesis user was identified as the main subject for this project. He will serve as the individual for whom the device will be designed. The client went through bilateral amputation on his upper limbs below the elbow. He has been using opening split hooks prosthesis on both arms for the last three years. Tasks that require certain degree of precision or movement are out of his capabilities. The development of this design intends to increase prosthesis functionality and foster independence in daily activities.

PROBLEM STATEMENT

Currently the client leads a highly independent and functional lifestyle. The use of the prosthesis permits him to perform most tasks involved in a daily routine. Yet, the task of changing a light bulb is out of the scope of his abilities. This serves as the motivation to design a device that theoretically will allow the user to change a light bulb considering the limitation of the prosthesis.

OBJECTIVE

Design an ergonomic tool that allows a hook prosthesis user to change a light bulb.

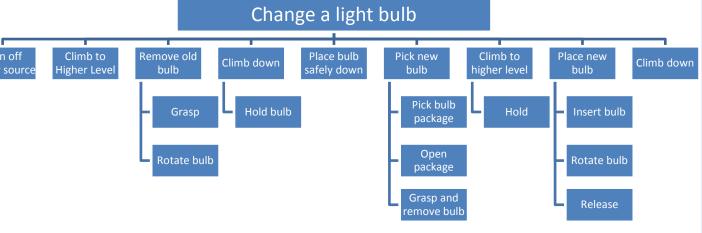
METHODOLOGY

OVERALL PROJECT FLOW CHART

Preliminary Cost Conceptualization Detailed Analysis Design

CONCEPTUALIZATION

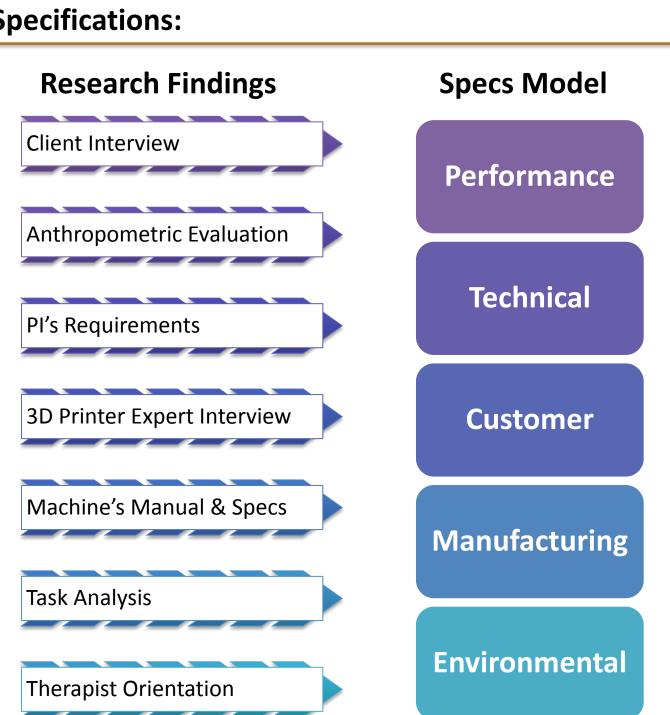
Task Analysis:

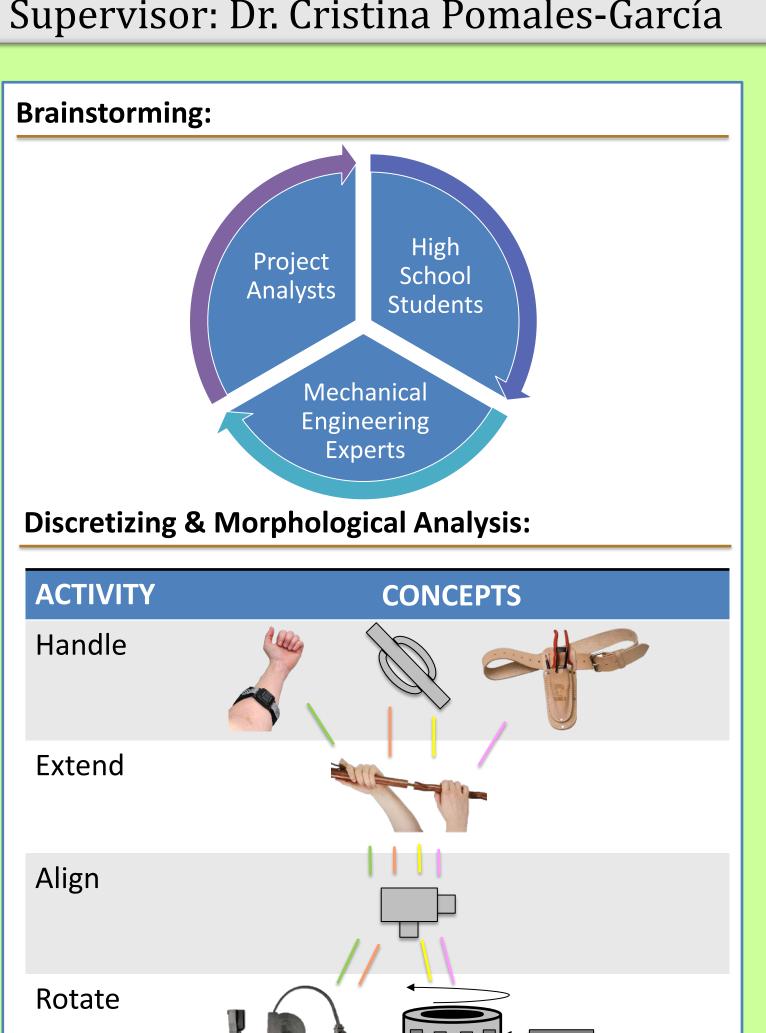


Risk Assessment Decision Matrix:

PROBABILITY	SEVERITY				
		Ш	Ш	IV	V
Frequent					
Probable					
Occasional					
Remote					
Improbable					

Specifications:

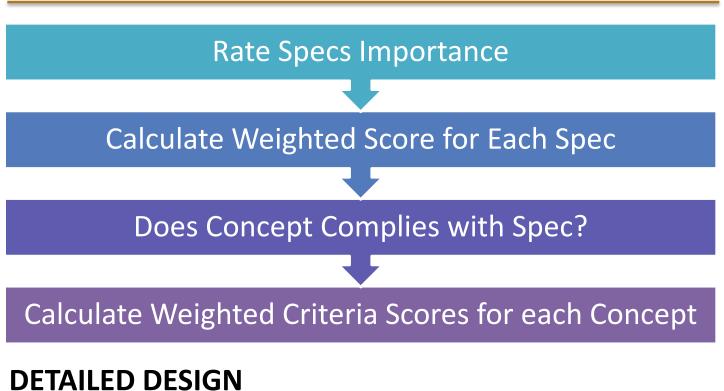




Weighted Criteria Assessment:

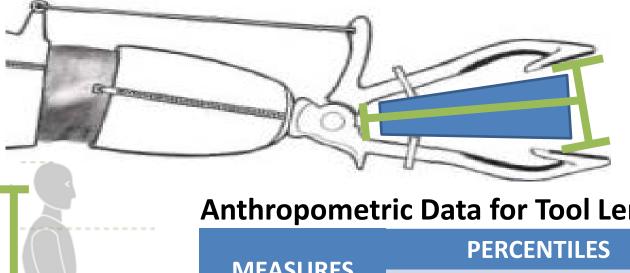
Grab

Bulb



Design for Usability:

Ergonomic Analysis for Handle Dimensions



		Anthropometric Data for Tool Lengt				
			MEASURES	PERCENTILES		
			IVIEASURES	1 – Women	99 - Men	
			Standing Height of Elbow (cm)	91.30	121.52	
			Standing Height of Eye (cm)	134.78	177.56	

Failure Analysis:

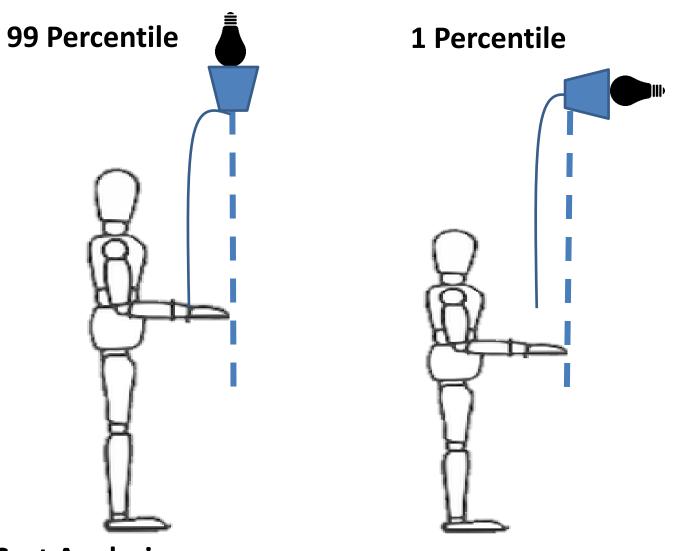
FAILURE SCENARIOS	DESIGN DECISIONS		
Assembly Breaks	Material Strength Analysis		
Dimensions don't fit	Press Fit Interference Tolerance		
Grip force breaks tool	Material Strength Analysis		
Tool slips from grip	Cubic shape; Handle Support		
Pulling force exceeds tolerance	Force Analysis		
Bulb does not rotate	Suction cup		
Device cannot hold the light bulb	Holder height exceeds half the bulb's length		

RESULTS

Champion Selection:

SPEC CATEGORY	WEIGHTED SCORE				
SI LC CAILGONI	C1	C2	C3	C4	
Performance	45	45	45	45	
Technical	77.1	77.1	77.1	77.1	
Customer	66.6	74.3	73.3	83.5	
Manufacturing	45.2	45.2	22.3	45.2	
Environment	12	12	12	12	
TOTAL	245.9	253.5	230.6	262.7	

Final Design:



Cost Analysis:

COST ACCUMULATION	COST MEASUREMENT		COST ASSIGNMENT
PLA Filament		\$28.30	
Adhesive	DM	\$0.90	
Cord		\$0.23	
Friction Material		\$2.97	
Warning Label		\$0.27	¢265.24
Recoil Winder		\$9.99	\$365.24
3D Printer Operator	DL	\$302.40	
Utilities		\$6.16	
Maintenance	ОН	\$0.28	
Depreciation		\$13.74	

6 **CONCLUSION & FUTURE WORK**

- This project showcase the necessity of devices that target people with prosthesis and enables them to realize everyday tasks.
- The 3D printer technology available is too costly for the production of this product, due to the amount of time it takes and the associated operation costs.
- Methodology used includes the perspective of all the stakeholders involved in the design process to develop a device that meets all ergonomic requirements.
- A thorough mechanical analysis will be realized to ensure the assembly stability and start the final testing of the prototype.

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